Efficiency and Stability in Large Matching Markets [*]

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Abstract

We study efficient and stable mechanisms in matching markets when the number of agents is large and individuals' preferences and priorities are drawn randomly. When agents' preferences are uncorrelated, then both efficiency and stability can be achieved in an asymptotic sense via standard mechanisms such as deferred acceptance and top trading cycles. When agents' preferences are correlated over objects, however, these mechanisms are either inefficient or unstable even in an asymptotic sense. We propose a variant of deferred acceptance that is asymptotically efficient, asymptotically stable and asymptotically incentive compatible. This new mechanism performs well in a counterfactual calibration based on New York City school choice data.

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1 Introduction

Assigning indivisible resources, such as housing, public school seats, employment contracts, branch postings and human organs, is an important subject for modern market design. Two central goals in designing such matching markets are efficiency and stability. Pareto efficiency means exhausting all gains from trade, a basic desideratum in any allocation problem. Stability means eliminating incentives for individuals to "block"—or circumvent—a suggested assignment. Not only is stability crucial for the long-term sustainability of a market, as pointed out by Roth and Sotomayor (1990), but it also guarantees a sense of fairness in eliminating so-called "justified envy."[1] For instance, in the school choice context, eliminating justified envy means that no student would lose a school seat to another student with a lower priority at that school.

Unfortunately, these two goals are incompatible (see Roth (1982)). Matching mechanisms such as serial dictatorship and top trading cycles (henceforth, TTC) attain efficiency but fail to be stable. Meanwhile, stable mechanisms such as Gale and Shapley's deferred acceptance algorithms (henceforth, DA) do not guarantee efficiency. In light of the impossibility of achieving both goals, the prevailing approach, particularly in the context of school choice, strives to attain one objective with the minimum possible sacrifice of the other goal. For instance, DA selects a stable matching that Pareto dominates all other stable matchings for the proposing side (Gale and Shapley, 1962). Similarly, there is a sense in which TTC, which allows agents to trade their priorities sequentially, satisfies efficiency at the minimal incidence of instabilities (Abdulkadiroglu, Che, Pathak, Roth, and Tercieux, 2017).[2]

While the tradeoff between efficiency and stability is well understood, it remains unclear how best to resolve the tradeoff when both goals are important. As noted above, the standard approach is to attain one goal at the minimal sacrifice of the other. Whether this is the best way to resolve the tradeoff is far from clear. For instance, one can imagine a mechanism that is neither stable nor efficient but may be superior to DA and TTC because it involves very little loss on either objective.

The purpose of the current paper is to answer these questions and, in the process, provide useful insights for practical market design. We address these questions in a model that has two main features. First, we consider markets that are "large" in the number of participants and in the number of object types. Large markets are clearly relevant in many settings.

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[1] See Balinski and Sönmez (1999) and Abdulkadiroglu and Sonmez (2003). This fairness property may be more important in applications such as school choice, where the supply side is under public control, so strategic blocking is not a serious concern.

[2] Abdulkadiroglu, Che, Pathak, Roth, and Tercieux (2017) shows that TTC is envy minimal in one-to-one matching in the sense that there is no efficient and strategy-proof mechanism that entails a smaller set of blocking pairs than TTC (smaller in the set inclusion sense) for all preferences, strictly so for some preferences.

For instance, in the US medical matching system, each year there are approximately 20,000 applicants for positions at 3,000 to 4,000 programs. In the New York City (NYC) school choice, approximately 80,000 students apply each year to over 700 high school programs. Second, we assume that agents' preferences are generated randomly according to some reasonable distributions. Specifically, we assume that each agent's utility for an object depends on a common component (that does not vary across agents) and an idiosyncratic component that is independently drawn at random (and thus varies across the agents), and the agents' priorities over objects are drawn identically and independently.[3]

Our framework enables us to perform meaningful "quantitative" relaxations of the two desiderata: we can search for mechanisms that are **asymptotically efficient**, in the sense that as the economy grows large, with high probability (i.e., approaching one), the proportion of agents who would gain discretely from a Pareto-improving assignment vanishes, and mechanisms that are **asymptotically stable**, in the sense that in a sufficiently large economy, with high probability, the proportion of agents who would have justified envy toward a significant number of agents vanishes.

Our first set of findings pertains to the tradeoff between DA and TTC. We find that, when agents' preferences for the objects are significantly correlated, the efficiency loss from DA remains significant even when the market grows large. Likewise, the instabilities in TTC do not disappear in large markets. The potential inefficiencies of DA and instabilities of TTC are well known from the existing literature; our novel finding here is that they remain "quantitatively" significant (even) in a large market.

These findings can be explained in intuitive terms. Suppose that the objects come in two tiers, high quality and low quality, and that every high-quality object is preferred to every low-quality object by each agent regardless of his idiosyncratic preferences. In this case, the (agent-proposing) DA has all agents compete first for every high-quality object before they compete for a low-quality object. Such competition means that in a stable matching—including agent-optimal stable matching—the outcome is dictated largely by how the objects rank the agents and not by how the agents rank the objects. Hence, the competition among agents entails significant welfare loss in the presence of the stability requirement.

Meanwhile, under TTC, many agents who are assigned low-quality objects exhibit justified envy toward a significant number of agents who obtain high-quality objects. The reason is that, even in a large economy, many of these latter agents obtain high-quality objects through the trading of their priorities. Typically, these agents have high priorities with the objects they are *trading off*, but they could well have very low priorities with the objects they are *trading in.* For this reason, TTC is asymptotically unstable.

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[3]We discuss in Sections 5 and 6 how our results carry over to richer environments in which agents' priorities are correlated.

Taken together, these two findings have an important practical market design implication, as they suggest that the standard approach of achieving one goal with a minimal sacrifice of the other may not be the best.[4]

Motivated by these results, we develop a new mechanism, called Deferred Acceptance with Circuit Breaker (DACB), that is both asymptotically efficient and asymptotically stable. This mechanism modifies DA to prevent participants from competing excessively. Specifically, all agents are ordered in some manner (for instance, at random), and following that order, each agent applies *one at a time* to the best object that has not yet rejected him.[5] The proposed object then accepts or rejects the applicant, much as in standard DA. If at any point, an agent applies to an object that holds an application, one agent is rejected, and the rejected agent in turn applies to the best object among those that have not rejected him. This process continues until an agent makes a certain "threshold" number κ of offers for the first time. Then, the stage is terminated at that point, and all tentative assignments up to that point become final. The next stage then begins with the agent who was rejected at the end of the last stage applying to the best remaining object and the number of proposals for that agent being reset to zero. The stages proceed in this fashion until no rejection occurs.

This "staged" version of DA resembles standard DA except for one crucial difference: The mechanism periodically terminates a stage and finalizes the tentative assignment up to that point. The event triggering the termination of a stage is an agent reaching a threshold number of offers. Intuitively, the mechanism activates a "circuit breaker" whenever the competition "overheats" to such an extent that an agent finds himself at the risk of losing an object he ranks highly to an agent who ranks it relatively lowly (more precisely, above the threshold rank). This feature ensures that each object assigned at each stage goes to an agent who ranks it relatively highly among the objects available at that stage.

Given the independent drawing of idiosyncratic shocks, the "right" κ is shown to be sub-linear in n no less than $\log^2(n)$ where n is the number of agents. Given the threshold, the DACB produces an assignment that is both asymptotically stable and asymptotically efficient. The analytical case for this mechanism rests on a limit analysis, but the mechanism performs well even away from the limit. Our simulation shows that, even for a moderately large market and a more general preference distribution, our mechanism performs considerably better than DA in terms of utilitarian welfare and entails significantly less stability loss than efficient mechanisms such as TTC.

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[4]In combinatorial assignment problems where transfers are not allowed, Budish (2011) makes a related point: he offers a market-like mechanism which makes relatively small compromises on efficiency and envy-freeness (while keeping desirable incentive properties) whereas known mechanisms satisfy one of these two objectives exactly.

[5]A version of DA in which offers are made according to a serial order was first introduced by McVitie and Wilson (1971).

One potential concern about this mechanism is its incentive property. While the mechanism is not strategy proof, the incentive problem does not appear to be severe. A manipulation incentive arises only when an agent is in a position to trigger the circuit breaker because the agent may then wish to apply to a safer object instead of a more popular one that has a high probability of rejecting him. The probability of this situation is one over the number of agents assigned in the current stage, which is on the order of n; hence, with a sufficient number of participants, the incentive issue is rather small.[6] Formally, we show that the mechanism induces truthful reporting as an ϵ-Bayes-Nash equilibrium.

Finally, another potential concern with this mechanism is the required bound on $\kappa \geq \log^2(n)$. In practice, applicants are often constrained to make a small number of applications, possibly below $\log^2(n)$ (a case in point is the high school assignment in NYC; see Section 6). To address such a situation, we generalize our mechanism so that for each κ, the termination of a stage is triggered *only* when at least $j \geq 1$ agents have each made more than κ offers. We provide a joint condition on (κ, j) that ensures that the generalized version of DACB is both asymptotically stable and asymptotically efficient. In particular, the required κ can be quite small for a sufficiently large j.

To study how our findings apply to a realistic market, we use the preference data supplied by the New York City Department of Education for public high school assignment during the 2009-2010 school year. Their main round employed a student-proposing DA in which each applicant submits a rank-order list (henceforth ROL) of up to 12 programs. Assuming the observed ROLs to prevail under alternative algorithms, we find a significant tradeff between efficiency and stability. First, on average 5,189 students would be Pareto-improved if they were rematched efficiently starting from the DA. Meanwhile, TTC would entail 18,943 students with justified envy.[7] This result is consistent with our theoretical finding that the tradeoffs do not disappear when the two prominent mechanisms are employed in a large market. Meanwhile, we show that DACB, with suitably-chosen parameters, would span a range of outcomes on the efficiency-stability frontier that are unattainable by the existing mechanisms. For reasons to be explained in detail, however, relying on the observed ROLs understates the tradeoff between DA and TTC. We therefore performed structural estimation of students' preferences using the method developed by Abdulkadiroglu, Agarwal, and Pathak (2015), and simulated

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[6]Unlike Azevedo and Budish (2015), the number of preference types grows without bound as the market grows large in the current model. Hence, their result on "strategy-proofness in the large" does not apply here. Nevertheless, it is simple to see from our arguments that DACB mechanism has a similar incentive property: truthful reporting is optimal in the limit economy against any *iid* distribution of reports provided that the distribution is one of those allowed in our paper. See also Remark 1.

[7]These figures are broadly in line with Abdulkadiroglu, Pathak, and Roth (2009)'s analysis of the 2006-2007 choice data. Note that their efficient matching does not coincide with TTC. Instead, Abdulkadiroglu, Pathak, and Roth (2009) produce efficient matching by first running DA and then running a Shapley-Scarf TTC based on the DA assignment.

alternative algorithms based on these estimates. Under these counterfactual analyses, TTC and DA perform considerably worse; for instance, about 29,293 students can be made better off from a Pareto-improving reassignment under DA while 21,029 applicants would feel justified envy under TTC.[8] By contrast, DACB performs impressively. For instance, it can yield an outcome considerably more efficient than DA with very little sacrifice in stability.

The DACB mechanism bears some resemblance to features observed in popular real-world matching algorithms. The "staged termination" feature is present in the school assignment program in China (Chen and Kesten (2017)). More important, the feature that suppresses excessive competition is present in the truncation of participants' choice lists, which is practiced in most real-world implementations of DA. We provide a rationale for this practice that is common in the actual implementation of DA but has thus far been difficult to rationalize (see Haeringer and Klijn (2009), Calsamiglia, Haeringer, and Klijn (2010), Pathak and Sömez (2013) and Ashlagi, Nikzad, and Romm (2015)). Indeed, we show that DA with an appropriate limit on the ROLs can, to some extent, achieve an asymptotically efficient and stable *equilibrium* outcome.

The present paper is related to the growing literature that studies large matching markets, particularly those with a large number of object types and random preferences; see Immorlica and Mahdian (2005), Kojima and Pathak (2009), Lee (2017), Knuth (1997), Pittel (1989), Ashlagi, Braverman, and Hassidim (2014), Ashlagi, Kanoria, and Leshno (2017), and Lee and Yariv (2017). The first three papers are largely concerned with the incentive issues arising in DA. The last five papers are concerned with the ranks of the partners achieved by the agents on the two sides of the market under DA. In particular, the last three papers study the large market efficiency performance of DA, and their relationship with the current paper will be discussed more fully below. Unlike these papers, our paper considers not only DA but also other mechanisms and adopts broader perspectives concerning both efficiency and stability.[9] Finally, Che and Tercieux (2017a,b) study large market properties of Pareto efficient mechanisms and provide some preliminary observations for the current paper.

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[8]As we explain in Section 6, the significant differences in the counterfactual analyses are attributed to the two methods which respectively provide lower- and upper-bound for the tradeoff between DA and TTC.

[9]Another strand of literature studying large matching markets considers a large number of agents matched with a finite number of object types (or firms/schools) on the other side; see Abdulkadiroglu, Che, and Yasuda (2015), Che and Kojima (2010), Kojima and Manea (2010), Azevedo and Leshno (2016) and Che, Kim, and Kojima (2013), Azevedo and Budish (2015), among others. The assumption of a finite number of object types makes substantial differences for both the analysis and the insights. The two strands of large matching market models capture issues that are relevant in different real-world settings and thus complement one another.

2 Model

A finite set of agents are assigned a finite set of objects, at most one object for each agent. Because our analysis will involve studying the limit of a sequence of such finite economies as they become large, it is convenient to index the economy by its size n. An n-**economy** $E^n = (I^n, O^n)$ consists of **agents** I^n and **objects** O^n, where $|I^n| = |O^n| = n$. The assumption that these sets are of equal size is purely for convenience. Provided that they grow at the same rate, our results hold even if the sets are not of equal size. For much of the analysis, we suppress the superscript n for notational convenience.

2.1 Preliminaries

Throughout, we will consider a general class of random preferences that allows for a positive correlation among agents on the objects. Specifically, each agent $i \in I^n$ receives utility from obtaining object type $o \in O^n$:

$$U_i(o) = U(u_o, \xi_{i,o}),$$

where u_o is a *common value*, and the *idiosyncratic shock* $\xi_{i,o}$ is a random variable drawn independently and identically from $[0, 1]$ according to the uniform distribution.[10]

The common values take finite values $\{u_1, ..., u_K\}$ such that $u_1 > ... > u_K$. For each n-economy, the objects O^n are partitioned into tiers, $\{O_1^n, ..., O_K^n\}$, such that each object in tier O_k^n yields a common value of u_k to the agent who is assigned it. We assume that the proportion of tier-k objects, $|O_k^n|/n$, converges to $x_k > 0$ such that $\sum_{k \in K} x_k = 1$. We sometimes use the notation $O_{\geq k}$ to denote the set of objects in $\cup_{\ell \geq k} O_\ell$. Similarly, let $O_{\leq k} := \cup_{\ell \leq k} O_\ell$. One can imagine an alternative model in which the common value is drawn randomly from $\{u_1, ..., u_K\}$ according to some distribution that converges to $\{x_1, ..., x_K\}$ as $n \to \infty$. Such a treatment will yield the same results as the current treatment, which can be regarded as considering each realization of such a random drawing.

We further assume that the function $U(\cdot, \cdot)$ takes values in $\mathbb{R}_+$, is strictly increasing in the common value and idiosyncratic shock and is continuous in the latter. The utility of remaining unmatched is assumed to be 0, which implies that each agent finds all objects acceptable.[11]

Next, the priorities agents have with different objects—or objects' "preferences" over agents—are drawn uniform randomly. Formally, we assume that individual i achieves a pri-

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[10]The uniform distribution assumption is without loss of generality provided that the type distribution is atomless and has full and bounded support, as one can always focus on the quantile corresponding to the agent's type as a normalized type and redefine the payoff function as a function of the normalized type.

[11]This feature does not play a crucial role in our results, which hold provided that a linear fraction of objects are acceptable to all agents.

ority score:

$$V_o(i) = V(\eta_{i,o}),$$

at object $o \in O$, where *idiosyncratic shocks* $\{\eta_{i,o}\}_{i,o}$ are iid random variables each drawn uniformly from $[0, 1]$. Although restrictive, the iid assumption captures a class of plausible circumstances under which a tradeoff between the two objectives persists and can be addressed more effectively by the novel mechanism we propose. Further, as explained in Section 5.1, our new mechanism can be easily modified to accommodate correlations in agents' priorities over objects. The function $V(\cdot)$ takes values in $\mathbb{R}_+$ and is strictly increasing and continuous. The utility of remaining unmatched is assumed to be 0, which implies that all objects find all individuals acceptable.

Fix an n-economy. A **matching** μ in an n-economy is a mapping $\mu : I \to O \cup \{\emptyset\}$ with the interpretation that agent i with $\mu(i) = \emptyset$ is unmatched. In addition, $\mu(i) \neq \mu(j)$ for any $j \neq i$, whenever $\mu(i) \neq \emptyset$ or $\mu(j) \neq \emptyset$. Let M_n denote the set of all matchings in n-economy. All of these objects depend on n, although their dependence is suppressed for notational convenience.

A **matching mechanism** is a function that maps states to matchings, where a state $\omega = (\{\xi_{i,o}, \eta_{i,o}\}_{i \in I, o \in O})$ consists of the realized profile $\{\xi_{i,o}\}_{i \in I, o \in O}$ of the idiosyncratic component of agents' payoffs and the realized profile $\{\eta_{i,o}\}_{i \in I, o \in O}$ of agents' priorities with the objects.[12] With a slight abuse of notation, we will use $\mu = \{\mu_\omega(i)\}_{\omega \in \Omega, i \in I}$ to denote a matching mechanism, which selects a matching $\mu_\omega(\cdot)$ in state ω. The set of all states is denoted by Ω. Let $\mathcal{M}_n$ denote the set of all matching mechanisms in n-economy. For convenience, we will often suppress the dependence of the matching mechanism on ω and on n.

For a limit analysis, we are interested in a sequence $\{\mu_n\}$ of matching mechanisms for the corresponding n-economies. We call such a sequence a **matching outcome**.

2.2 Welfare and Fairness Concepts in Large Markets

A matching $\mu \in M_n$ is Pareto efficient if there is no other matching $\mu' \in M_n$ such that $U_i(\mu'(i)) \geq U_i(\mu(i))$ for all $i \in I$ and $U_i(\mu'(i)) > U_i(\mu(i))$ for some $i \in I$. A matching mechanism $\mu \in \mathcal{M}_n$ is Pareto efficient if, for each state $\omega \in \Omega$, the matching it induces, i.e., $\mu_\omega(\cdot)$, is Pareto efficient. Let $\mathcal{M}_n^*$ denote the set of all Pareto-efficient mechanisms in the n-economy. A matching μ at a given state is stable if there is no pair (i, o) such that

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[12]Note that matching mechanisms depend on cardinal preferences/priorities in our model, whereas standard mechanisms such as top trading cycles and deferred acceptance depend only on ordinal preferences and priorities. Obviously, cardinal preferences/priorities induce ordinal preferences/priorities, and the current treatment clearly encompasses these mechanisms. We focus on cardinal utilities and priorities to operationalize the asymptotic notions of efficiency and stability. Our results do not depend on the particular cardinalization of utilities.

$U_i(o) > U_i(\mu(i))$ and $V_o(i) > V_o(\mu(o))$—i.e., no pair wishes to match with each other rather than their partners in matching μ. A matching mechanism $\mu \in \mathcal{M}_n$ is stable if, for each state $\omega \in \Omega$, the matching it induces, $\mu_\omega(\cdot)$, is stable.

Throughout, we will invoke the following implication of Pareto efficiency.

LEMMA 1 (Che and Tercieux (2017b)). *For any Pareto-efficient matching outcome* $\{\mu_n\}$,

$$\frac{\sum_{i \in I} U_i(\mu_n(i))}{n} \xrightarrow{p} \sum_{k=1}^{K} x_k U(u_k, 1).$$

Notice that the right-hand side gives the (normalized) total utility that would be obtained if all agents attained the highest possible idiosyncratic value; hence, it is the utilitarian upper bound. The lemma states that the aggregate utilities agents enjoy in any Pareto efficient mechanism approach that bound in probability as $n \to \infty$. Recall that our model allows for agents' preferences to be correlated; in particular agents tend to prefer objects with higher common value than lower common value. The striking implication of Lemma 1 is that this conflict of interests does not cause a significant welfare loss if the allocation is Pareto efficient. As will be seen, the same will not be the case with a stable matching.

We next discuss how efficiency and stability can be weakened in the large market setting. We say that a matching outcome $\{\mu_n\}$ is **asymptotically efficient** if, for any $\epsilon > 0$ and for any matching outcome $\{\mu'_n\}$ that for each n-economy Pareto dominates $\{\mu_n\}$:

$$\frac{|I_\epsilon(\mu'_n|\mu_n)|}{n} \xrightarrow{p} 0 \text{ as } n \to \infty,$$

where $I_\epsilon(\mu'_n|\mu_n) := \{i \in I | U_i(\mu_n(i)) < U_i(\mu'_n(i)) - \epsilon\}$ is the set of agents who would benefit more than ϵ by switching from μ_n to μ'_n. In words, a matching outcome is asymptotically efficient if the fraction of agents who could benefit discretely from any Pareto-improving rematching vanishes in probability as the economy becomes large.

The notion of stability can be weakened in a similar way. We say that a matching outcome $\{\mu_n\}_n$ is **asymptotically stable** if, for any $\epsilon > 0$:

$$\frac{|J_\epsilon(\mu_n)|}{n(n-1)} \xrightarrow{p} 0 \text{ as } n \to \infty,$$

where $J_\epsilon(\mu_n) := \{(i, o) \in I \times O | U_i(o) > U_i(\mu_n(i)) + \epsilon \text{ and } V_o(i) > V_o(\mu_n(o)) + \epsilon\}$ is the set of ϵ-**blocks**—namely, the set of pairs of an agent and an object who would each gain ϵ or more from matching with one another rather than matching according to μ_n. Asymptotic stability requires that for any $\epsilon > 0$, the fraction of these ϵ-blocks as a share of all $n(n-1)$ "possible" blocking pairs vanishes in probability as the economy grows large. It is possible even in an

asymptotically stable matching that some agents are willing to ϵ-block with a large number of objects, but the fraction of such agents should vanish in probability.

This can be stated more formally. For any $\epsilon > 0$, let $\hat{O}^i_\epsilon(\mu_n) := \{o \in O | (i,o) \in J_\epsilon(\mu_n)\}$ be the set of objects agent i can form an ϵ-block with against μ_n. Then, a matching is asymptotically stable if and only if the set of agents who can form an ϵ-block with a non-vanishing fraction of objects vanishes in probability, i.e., for any $\epsilon, \delta > 0$:

$$\frac{|I_{\epsilon,\delta}(\mu_n)|}{n} \xrightarrow{p} 0 \text{ as } n \to \infty,$$

where $I_{\epsilon,\delta}(\mu_n) := \left\{ i \in I \middle| |\hat{O}^i_\epsilon(\mu_n)| \geq \delta n \right\}$. If, as is plausible in many circumstances, agents form ϵ-blocks by randomly sampling a finite number of potential partners (i.e., objects), asymptotic stability would mean that only a vanishing proportion of agents will succeed in finding blocking partners in a large market.

A similar implication can be drawn in terms of fairness. Asymptotic stability of matching implies that only a vanishing proportion of agents would have (a discrete amount of) justified envy toward a non-vanishing proportion of agents. If an individual becomes aggrieved from justifiably envying, for example, someone from a random sample of finite agents (e.g., friends or neighbors), then the property will guarantee that only a vanishing fraction of individuals will suffer significant aggrievement as the economy grows large.

2.3   Two Prominent Mechanisms

As mentioned above, the existing literature and school choice programs in practice center on the following two mechanisms, and the tradeoff between the two will be an important part of our inquiry.

☐ **Top Trading Cycles (TTC) Mechanism:**

The Top Trading Cycles algorithm, originally introduced by Shapley and Scarf (1974) and later adapted by Abdulkadiroglu and Sonmez (2003) to the school choice context, has been an influential method for achieving efficiency.[13] The mechanism has some notable applications. For instance, the TTC mechanism was used until recently to assign students to public high schools in the New Orleans school system. A version of TTC is also used for kidney exchange among donor-patient pairs with incompatible donor kidneys (see Sonmez and Unver (2011)).

The TTC algorithm (defined by Abdulkadiroglu and Sonmez (2003)) proceeds in multiple rounds as follows. In Round $t = 1, ...,$ each individual $i \in I$ points to his most preferred object. Each object $o \in O$ points to the individual who has the highest priority with that

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[13]The original idea is attributed to David Gale by Shapley and Scarf (1974).

object. Because the numbers of individuals and objects are finite, the directed graph thus obtained has at least one cycle. Every individual who belongs to a cycle is assigned the object at which he is pointing. The assigned individuals and objects are then removed. The algorithm terminates when all individuals have been assigned; otherwise, it proceeds to Round $t + 1$. This algorithm terminates in finite rounds. The TTC mechanism selects a matching via this algorithm for each realization of individuals' preferences and objects' priorities.

As is well known, the TTC mechanism is Pareto efficient and strategy proof (i.e., it is a dominant strategy for agents to report their preferences truthfully). As mentioned, TTC is unstable but it is constrained-stable in the sense that it is justified-envy minimal among Pareto efficient and strategy proof mechanisms (see Abdulkadiroglu, Che, Pathak, Roth, and Tercieux (2017)).

□ The Deferred Acceptance (DA) Mechanism

The best-known mechanism for attaining stability is the deferred acceptance algorithm. Since introduced by Gale and Shapley (1962), the mechanism has been applied widely in a variety of contexts. The medical matching system in the US and other countries adopt DA for assigning doctors to hospitals for residency programs. The school systems in Boston and New York City use DA to assign eighth-grade students to public high schools (see Abdulkadiroglu, Pathak, and Roth (2005) and Abdulkadiroglu, Pathak, Roth, and Sonmez (2005)).

For our purpose, it is more convenient to define DA as proposed by McVitie and Wilson (1971), proceeding in multiple steps as follows:

Step 0: Linearly order individuals in I from 1 to n.

Step 1: Let individual 1 make an offer to his favorite object in O. This object tentatively holds individual 1; go to Step 2.

Step $i \geq 2$: Let individual i make an offer to his favorite object o in O from among the objects to which he has not yet made an offer. If o does not have a tentatively accepted agent, then o tentatively accepts i. If the algorithm is at Step n, end the algorithm; otherwise, iterate to Step $i + 1$. If, however, o has a tentatively accepted agent—call him i^*—object o chooses between i and i^* and tentatively accepts the one with the higher priority (or one more preferred by o) and rejects the other. The rejected agent is named i, and we return to the beginning of Step i.

Note that the algorithm iterates to Step $i + 1$ *only* after all offers made in Step i are processed and there are no more rejections. The algorithm terminates in n Steps, with finite offers having been made. The DA mechanism selects a matching via this process for each realization of individuals' preferences and objects' priorities.

As is well known, the (agent-proposing) DA mechanism selects a stable matching that Pareto dominates all other stable matchings, and it is also strategy proof (Dubins and Freed-

man (1981); Roth (1982)). However, the DA matching is not Pareto efficient, meaning that the agents may all be better off from another matching (which is not stable).

3   Efficiency and Stability with Uncorrelated Preferences

As a benchmark, we first consider the case in which the participants' preferences for the objects are uncorrelated. That is, the support of the common component of the agents' utilities is degenerate, with a single tier $K = 1$ for the objects. This case has been considered extensively in the computer science literature (Wilson (1972), Pittel (1989), Pittel (1992), Frieze and Pittel (1995), Knuth (1997)). In particular, those papers characterize the asymptotics of the ranks enjoyed by individuals and by the objects under DA. Specifically, let R_i^{DA} denote the rank enjoyed by individual i under DA; that is, $R_i^{DA} = \ell$ if i obtains his ℓth most favorite object under DA. Similarly, we let R_o^{DA} denote the rank enjoyed by object o under DA. We will repeatedly utilize the following results.

LEMMA 2 (Pittel (1989, 1992)). *Assume $K = 1$. Then,*

$$\Pr\left\{\max_{i \in I} R_i^{DA} \leq \log^2(n)\right\} \to 1 \ as \ n \to \infty.$$

In addition, for any $\delta > 0$,

$$\Pr\left\{\frac{1}{n} \sum_{o \in O} R_o^{DA} \leq (1+\delta)\frac{n}{\log(n)}\right\} \to 1 \ as \ n \to \infty.$$

Since both $\log^2(n)$ and $n/\log(n)$ are small relative to n as $n \to \infty$, this lemma implies that the agents and objects attain both very high payoffs in a large market. In fact, both DA and TTC involve little tradeoff when preferences are uncorrelated:

THEOREM 1. *If $K = 1$, then any outcome of Pareto-efficient mechanism, and hence that of TTC, is asymptotically stable, and the outcome of DA is asymptotically efficient.*[14]

PROOF. The asymptotic stability of a Pareto-efficient mechanism follows from Lemma 1, which implies that for any $\epsilon > 0$, the proportion of the set $I_\epsilon(\tilde{\mu})$ of agents who realize payoffs less than $U(u_1, 1) - \epsilon$ in any Pareto-efficient matching mechanism $\tilde{\mu} \in \mathcal{M}_n^*$ vanishes in probability as $n \to \infty$. Since $I_{\epsilon,\delta}(\tilde{\mu}) \subset I_\epsilon(\tilde{\mu})$, asymptotic stability then follows.

The asymptotic efficiency of DA is shown as follows. Let E_1 be the event that all agents are assigned objects in DA that they rank within $\log^2(n)$. By Lemma 2, the probability of

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[14]Using Wilson (1972), one can show that the result of the theorem holds regardless of the objects' priorities. Hence, there is no need here to draw these randomly.

that event goes to 1 as $n \to \infty$. Now, fix any small $\epsilon > 0$ and let E_2 be the event that all agents would receive a payoff greater than $U(u_1, 1) - \epsilon$ from each of their top $\log^2(n)$ objects. Because for any $\delta > 0$, $\log^2(n) \leq \delta |O_1| = \delta n$ for a sufficiently large n, by Lemma S1-(i) in Online Appendix S.1, the probability of that event goes to 1 as $n \to \infty$. Clearly, whenever both events occur, all agents will receive a payoff greater than $U(u_1, 1) - \epsilon$ under DA. As the probability of both events occurring goes to 1, the DA mechanism is asymptotically efficient.[15]
$\square$

It is worth noting that the tradeoffs of the two mechanisms do not disappear *qualitatively* even in large markets: DA remains inefficient and TTC remains unstable even as the market grows large. In fact, given random priorities on the objects, the acyclicity conditions required for the efficiency of DA and stability of TTC according to Ergin (2002) and Kesten (2006), respectively, fail almost surely as the market grows large. What Theorem 1 suggests is that the tradeoff disappears *quantitatively*, provided that the agents have uncorrelated preferences.

Uncorrelated preferences mean that the conflicts that agents may have over the goods disappear as the economy grows large, as each agent is increasingly able to find an object that he likes that others do not. This, in turn, implies that the agents can attain high payoffs, in fact, arbitrarily close to their payoff upper bound as $n \to \infty$ under DA. This eliminates (probabilistically) the possibility that a significant fraction of agents can be made discretely better off from rematching, thus explaining the asymptotic efficiency of DA. Similarly, under TTC, the agents enjoy payoffs that are arbitrarily close to their payoff upper bound as $n \to \infty$, which guarantees that the number of agents who each would justifiably envy a significant number of agents vanishes in the large market. Hence, TTC is asymptotically stable.

4 Efficiency and Stability under General Preferences

We now consider our main model in which agents' preferences are correlated. In particular, we assume that some objects are regarded by "all" agents as better than the other objects. This situation is common in many contexts such as school assignment, as students and parents tend to value similar qualities about schools (teacher and peer qualities, safety, etc.).

To consider such an environment in a simple way, we suppose that the objects are divided into two tiers O_1 and O_2 such that $|I| = |O_1| + |O_2| = n$. As assumed above, $\lim_{n \to \infty} \frac{|O_k|}{n} =$

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[15]Our notion of efficiency focuses on one side of the market: the individuals' side. It is worth noting here that even if we were to focus only on the other side, the objects' side, asymptotic efficiency would still follow from the second part of Lemma 2 despite our use of a DA in which individuals are the proposers (see the proof of Proposition 1 for a formal argument). This also implies that under a DA in which schools are the proposers, in our environment (in which priorities are drawn randomly), asymptotic efficiency on the individual side can be achieved. Thus, any stable mechanism is asymptotically efficient in this context.

$x_k > 0$ for $k = 1, 2$. Our arguments in this section generalize in an obvious way to a case with more than two tiers. In addition, we assume that every agent considers each object in O_1 to be better than each object in O_2: $U(u_1, 0) > U(u_2, 1)$. In the school choice context, this feature corresponds to a situation in which students agree on the preference rankings over schools across different districts but may disagree on the rankings of schools within each district. Agents' priorities with objects are given by idiosyncratic random shocks, as assumed above.

In this environment, we will show that the standard tradeoff between DA and TTC extends to large markets even in the asymptotic sense—namely, DA is not asymptotically efficient and TTC is not asymptotically stable.

4.1   Asymptotic Instability of TTC

Our first result is that, with correlated preferences, TTC fails to be asymptotically stable.

THEOREM 2. *In our model with two tiers, the matching outcome of TTC is not asymptotically stable. More precisely, there exists $\epsilon > 0$ such that:*

$$\frac{|J_\epsilon(TTC)|}{n(n-1)} \overset{p}{\not\to} 0.$$

We provide the main idea of the proof here; the full proof is in Online Appendix S.2. In essence, the asymptotic instability of TTC arises from the key feature of this mechanism. In TTC, agents attain efficiency by "trading" among themselves objects where they have high priorities. This process entails instabilities because an agent could have a very low priority with an object and yet could obtain it if he has a high priority with an object that is demanded by another agent who has a high priority with the former object. This insight is well known but silent on the magnitude of the instabilities for a large economy. Recall, for instance, that instabilities are not significant in a large economy when agents' preferences are uncorrelated. In that case, the agents' preferences do not conflict with one another, and they all attain close to their "bliss" payoffs in TTC, resulting in only a vanishing proportion of agents justifiably envying any significant number of agents.

The matters are different, however, when their preferences are correlated. In the two-tier case, for instance, a large number of agents are assigned tier 2 objects, and they all envy the agents who obtain tier 1 objects. The asymptotic stability of the mechanism then depends on how much of this envy is justified, namely how many of the envying agents have higher priorities than those envied.

This latter question boils down to the length of the cycles through which the latter agents are assigned in the TTC mechanism. Call a cycle of length two—namely, an agent points to

14
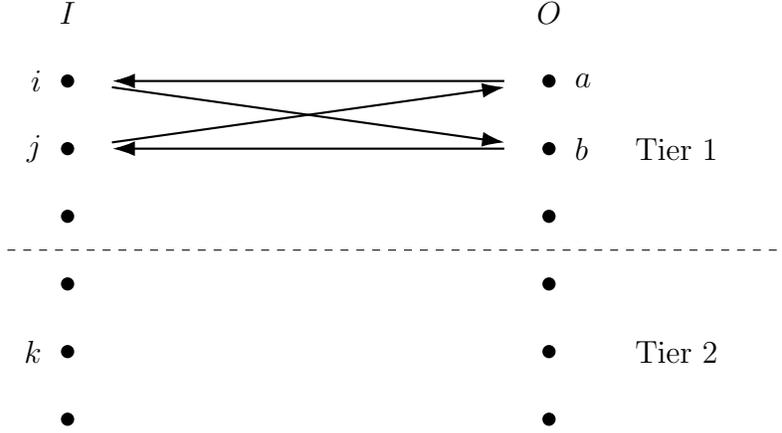
Figure 1: Possible justified envy by k toward j

an object, which in turn points back to that agent—a **short cycle** and any cycle of length greater than two a **long cycle**. Intuitively, the agents who are assigned via short cycles are likely to have high priorities with their assigned objects.[16] By contrast, the agents who are assigned via long cycles are unlikely to have high priorities. Agents in the long cycles tend to have high priorities with the objects they *trade up* (because the objects must have pointed to them), but they could have very low priorities with the objects they *trade in*. For instance, in Figure 1, agent i need not have a high priority with b, although agent j does. In fact, their priorities at the objects they eventually receive play no (contributory) role in the formation of such a cycle.[17] Hence, their priorities with the objects they receive (in O_1) are at best simple *iid* draws, and hence each of them has a one-half probability of having a higher priority than an agent who receives a tier 2 object. This suggests that any agent receiving a tier 2 object will have on average a significant amount of justified envy toward a half of those who receive tier 1 objects via long cycles. In Figure 1, agent k (who receives a tier 2 object) has probability $1/2$ of having a higher priority at b than agent i.

The crucial part of the proof of Theorem 2 is to show that the number of agents assigned tier 1 objects via long cycles is significant—i.e., the number does not vanish in probability as $n \to \infty$. While this result is intuitive, its proof is not trivial. By an appropriate extension of "random mapping theory" (see Bollobas (2001, Chapter 14)), we can compute the expected number of tier 1 objects that are assigned via long cycles in the first round of TTC. But,

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[16]In fact, any agent assigned via a short cycle cannot be a target of justified envy. Suppose i is assigned o via a short cycle. Then, any agent j with a higher priority at o than i could have gotten o ahead of i, so j could not have envied i.

[17]If anything, the role of their priorities is negative. That an agent is assigned via a long cycle, as opposed to a short cycle, means that she does *not* have the highest priority with the object she receives in that round.

these objects comprise a vanishing proportion of n as the market becomes large. However, extending the random mapping analysis to the subsequent rounds of TTC is difficult because the distribution of the preferences and priorities of the agents remaining after the first round depends on the specific realization of the first round of TTC. In particular, their preferences for the remaining tier 1 objects are no longer *iid*. This conditioning issue requires a deeper understanding of the precise random structure through which the algorithm evolves over rounds. We do this in Che and Tercieux (2017a). In particular, we establish that the *number* of objects (and thus of agents) assigned in each round of TTC follows a simple Markov chain, implying that the number of agents cleared in each round is not subject to the conditioning issue. However, the *composition* of the cycles, in particular short versus long cycles, is subject to the conditioning issue. Nevertheless, in the Online Appendix S.3, we are able to bound the number of short cycles formed in each round of TTC, and this bound, combined with the Markov property of the number of objects assigned in each round, produces the result.

4.2 Asymptotic Inefficiency of DA

Given correlated preferences, we also find that the inefficiency of DA is significant in the large market:

THEOREM 3. *In our two-tier model, the matching outcome of DA is not asymptotically efficient. More precisely, there exist $\epsilon > 0$ and a matching outcome μ that Pareto dominates DA in each n-economy such that:*

$$\frac{|I_\epsilon(\mu|DA)|}{n} \xrightarrow{p} \not\to 0.$$

as $n \to \infty$.

The DA matching Pareto dominates all other stable matchings, as shown by Gale and Shapley (1962). Hence, any matching outcome μ that Pareto dominates DA and satisfies the property stated in Theorem 3 will Pareto dominate any stable matching outcome and satisfy the same property. Thus, we obtain:

COROLLARY 1. *Any stable matching outcome fails to be asymptotically efficient in our two-tier model.*

The proof of Theorem 3 is in the Online Appendix S.4; we explain its intuition here. When the agents' preferences are correlated, agents tend to compete excessively for the same set of objects, and this competition results in a significant welfare loss under a stable mechanism. To see this intuition more clearly, recall that all agents prefer every object in O_1 to any object in O_2. This means that in the DA, they all first apply for objects in O_1 before they ever apply for any object in O_2. The first phase of the DA is then effectively a sub-market consisting

of all agents and tier 1 objects with random preferences and priorities. As there are excess agents of size $|I| - |O_1|$, which grows linearly in n, even those agents who are fortunate enough to receive tier 1 objects must have competed to such an extent that they would have suffered a significant welfare loss.[18]

Indeed, note that each of the agents who is eventually assigned an object in O_2 must have made $|O_1|$ offers to the objects in O_1 before he/she is rejected by all of them. This means that each object in O_1 must receive at least $|I| - |O_1|$ offers. Then, from an agent's perspective, to be assigned an object in O_1, he must survive competition from at least $|I| - |O_1| = |O_2|$ other agents. The odds of this equal $\frac{1}{|O_2|+1}$, as the agents are all ex ante symmetric. Hence, the odds that an agent is rejected by his top δn choices, for any $\delta > 0$, is at least

$$\left(1 - \frac{1}{|O_2| + 1}\right)^{\delta n} \to \left(\frac{1}{e}\right)^{\frac{\delta}{x_2}}, \tag{1}$$

because $\frac{|O_2|}{n} \to x_2$ as $n \to \infty$. Note that this probability approaches one as δ becomes sufficiently small. This probability is not conditional on an agent being assigned a tier 1 object. However, each agent *is* assigned a tier 1 object with positive probability (close to $x_1 > 0$). Hence, for the unconditional probability of an agent making at least δn offers to be close to one, the probability of making that many offers even *conditional* on him receiving a tier 1 object must also be positive. As shown more precisely in Online Appendix S.4, therefore, even those agents who are fortunate enough to receive tier 1 objects must suffer a significant number of rejections with nonvanishing probability. These agents will therefore attain payoffs that are, on average, bounded away from $U(u_1, 1)$.

This outcome is inconsistent with asymptotic efficiency. To see this, suppose that, once objects are assigned through DA, the Shapley-Scarf TTC is run with their DA assignment serving as the agents' initial endowment. The resulting reassignment Pareto dominates the DA assignment. Further, it is Pareto efficient. Then, by Lemma 1, with probability going to 1, a fraction arbitrarily close to 1 of agents assigned to O_1 objects enjoy payoffs arbitrarily close to $U(u_1, 1)$ when the market grows large. This implies that a significant number of agents will enjoy a significant welfare gain from a Pareto-dominating reassignment.[19]

It is worth emphasizing that the significant welfare loss under DA is caused by the excessive

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[18]This result is obtained by Ashlagi, Kanoria, and Leshno (2017) and Ashlagi, Braverman, and Hassidim (2014) building on the algorithm originally developed by Knuth, Motwani, and Pittel (1990) and Immorlica and Mahdian (2005). Here, we provide a direct proof that is much simpler. This proof is sketched here and detailed in Online Appendix S.4.

[19]This result is related to Ashlagi and Nikzad (2015) who show that many pairs of students would benefit from directly exchanging assignments ex post when there is a shortage of seats. Besides the "types" of reassignment, the notion of welfare gain is different, however: we focus on the agents who would benefit "discretely" from reassignment.

competition forced upon the agents. This observation serves as a key motivation for designing a new mechanism that, as we show next, is asymptotically efficient and asymptotically stable.

5 Deferred Acceptance with Circuit Breaker

As we just saw, two most prominent mechanisms fail to achieve asymptotic efficiency and asymptotic stability. Is there a mechanism that satisfies both properties? We next propose one such mechanism.[20] To be more precise, we define a class of mechanisms indexed by some positive integer κ (allowed to be ∞). For a given κ, the new mechanism then modifies (the McVitie-Wilson version of) DA to finalize tentative assignments whenever an agent has made κ offers for the first time. We will show how κ can be chosen to achieve our goal. For further applicability, we generalize the mechanism so that the assignment is triggered when a certain number $j \geq 1$ of agents have each made κ offers.[21] For expositional clarity, we begin with the simplest version and present the generalized version in a second step.

5.1 Basic Algorithm

Given a value κ, the DA with Circuit Breaker (DACB) begins by collecting agents' preference rankings of objects. Next, the agents are given serial orders: $1, \ldots n$. We do not specify how the **serial orders** of the agents are determined, except to assume that they admit **basic uncertainty** from the agents' perspective: *for each $k = 1, ..., n$, the probability that any agent i receives the serial order k goes to zero as $n \to \infty$.* This property holds trivially if the agents' serial orders are chosen uniform randomly but holds much more generally, for instance, even when an agent could anticipate this distribution to some extent based on his priorities.

Given the agents' preference rankings and serial orders, DACB with index κ is defined recursively on triplets: the sets $\hat{I}$ and $\hat{O}$ of remaining agents and objects, respectively, and a counter for each agent that records the number of offers he has made so far. We first initialize $\hat{I} = I$ and $\hat{O} = O$ and set the counter for each agent to zero.

Step $i \geq 1$: The agent with index i (i.e., i-th lowest serial order) in $\hat{I}$ applies to his favorite object o among those in $\hat{O}$ to which he has not yet applied. The counter for that

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[20]The feasibility of attaining both asymptotic efficiency and asymptotic stability can be seen directly by appealing to the Erdös-Renyi theorem. Exploiting this theorem, one can construct a mechanism that is asymptotically efficient and asymptotically stable. However, this mechanism would not be desirable for several reasons. In particular, as we discuss in the Online Appendix S.5, it would not have good incentive properties. By contrast, the mechanism that is proposed here does have a good incentive property, as we show below.

[21]The extended version of DACB has the additional benefit of making the mechanism robust when there are (a small number of) agents who may act irrationally and trigger the circuit-breaker prematurely. Clearly, the extended version of the DACB algorithm is not significantly affected by the presence of such agents.

agent increases by one. If o is not tentatively holding any agent, then o tentatively holds that agent, and the algorithm iterates to Step $i + 1$. (The algorithm is terminated if no more students are left or if $i = n$). If o is already holding an agent tentatively, it tentatively accepts the agent with a higher priority and rejects the other. There are two cases to consider.

1. Suppose the counter for the agent who has just applied is equal to κ. Then each agent who is tentatively assigned an object in Steps $1, ..., i$ is assigned that object. Reset $\hat{O}$ to be the set of unassigned objects and $\hat{I}$ to be the set of unassigned agents. Reset the counter for the agent rejected at step i to zero. If $\hat{I}$ is non-empty, return to Step 1; otherwise, terminate the algorithm.

2. Suppose the counter for the agent who has just applied is strictly below κ. Then, if he has applied to an already matched object, we return to the beginning of Step i where—instead of the agent with serial order i—the agent rejected by o makes an offer.

The Steps $1, ..., i$, taken until a threshold κ is reached, are called a **Stage**. Specifically, a Stage begins whenever $\hat{O}$ is reset, and the Stages are numbered $1, 2, ...$ serially. Each Stage has finite Steps, and there will be finite Stages. This algorithm modifies the McVitie and Wilson (1971) version of DA such that tentative assignments are periodically finalized.

The DACB mechanism spans a broad range of mechanisms indexed by κ. If $\kappa = 1$, then each Stage consists of one Step, wherein an agent acts as a dictator with respect to the objects remaining at that Stage. Hence, with $\kappa = 1$, the DACB reduces to a serial dictatorship mechanism. A serial dictatorship is efficient but obviously fails to satisfy (even asymptotic) stability because it completely ignores agents' priorities with the objects. By contrast, if $\kappa = +\infty$, then the DACB mechanism coincides with the DA mechanism. As demonstrated above, DA is stable but fails to be asymptotically efficient. Thus, intuitively, κ should be sufficiently large so that agents compete enough (otherwise, we would not achieve asymptotic stability) but sufficiently small so that they do not compete excessively (otherwise, the outcome would not be asymptotically efficient).

The next theorem provides the relevant lower and upper bounds on κ to ensure that the DACB mechanism attains both asymptotic efficiency and asymptotic stability.

THEOREM 4. *If $\kappa(n) \geq \log^2(n)$ and $\kappa(n) = o(n)$, then the matching outcome of DACB is asymptotically efficient and asymptotically stable.*[22]

PROOF. See Appendix.$\square$

Theorem 4 shows that DACB is superior to DA and TTC in large markets when the designer cares about both asymptotic efficiency and asymptotic stability.

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[22]Recall that $\kappa(n) = o(n)$ means that $\lim_{n \to \infty} \frac{\kappa(n)}{n} = 0$

Roughly speaking, the idea of DACB is to endogenously segment the market into "balanced" submarkets. To appreciate this idea, consider a thought experiment wherein the designer partitions agents (for example, randomly) into K groups with the number of agents I_k in group $k = 1, ..., K$ set equal to $|O_k|$; the designer then runs DA separately for each submarket consisting of I_k and O_k. Lemma 2 then implies that, with high probability,[23] all except for a vanishing fraction of agents would enjoy idiosyncratic payoffs and priorities arbitrarily close to the upper bounds in each submarket.[24] Asymptotic efficiency and asymptotic stability would thus follow. In particular, the segmentation avoids the significant welfare loss that would result from excessive competition for top-tier objects under DA (without segmentation). In practice, however, such a precise segmentation would be difficult to achieve because the designer would not know the exact preference structure of the agents; for instance, the designer would not know exactly which set of objects belongs to the top tier, which set belongs to the second tier, and so on. Moreover, such an exogenous segmentation could be highly susceptible to possible misspecification of segments by the designer. DACB, with its periodic clearing of markets, achieves the necessary segmentation of the market *endogenously*, without exact knowledge about agents' preferences by the designer.

How the segmentation works under DACB—namely the proof of Theorem 4—is explained as follows. First, as $\kappa(n)$ is sublinear in n (i.e., $\kappa(n) = o(n)$), with probability approaching one as $n \to \infty$, *all* agents find their $\kappa(n)$ most preferred objects to be in O_1 (see Lemma S1 in Online Appendix S.1). Therefore, all first $|O_1|$ agents in terms of serial order would compete for objects in O_1. Since $\kappa(n) \geq \log^2(n)$, Lemma 2 implies that, with high probability, the first $|O_1|$ Steps of DACB would proceed without the threshold $\kappa(n)$ being reached by any agent, meaning that with high probability, the first $|O_1|$ Steps would proceed precisely the same as if DA were run on the "hypothetical" submarket consisting of the first $|O_1|$ agents and the objects O_1. It then follows that with high probability, the entire O_1 would be assigned without triggering the termination of the first Stage.

Next comes Step $|O_1|+1$. By then, with high probability, all objects in O_1 are assigned, and hence given the first observation (i.e., that all agents find their $\kappa(n)$ most preferred objects to be in O_1), some agent must be rejected at least $\kappa(n)$ times before the Step $|O_1|+1$ concludes, and thus the end of Stage 1 must be triggered at that Step. Since, with high probability, all payoffs of objects in O_1 are arbitrarily close to the upper bound by the end of Step $|O_1|$ (by the second part of Lemma 2), this must also be the case by the end of Step $|O_1| + 1$ because

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[23]For a sequence of events E_n, we say that this sequence occurs *with high probability* if $\Pr(E_n)$ converges to 1 as n goes to infinity.

[24]Recall from Lemma 2 that all individuals and objects except for a fraction vanishing in probability enjoy ranks that are sublinear in n. This in turn implies that all but a vanishing fraction of these agents attain idiosyncratic payoffs arbitrarily close to the upper bounds (see Lemma S1 in Online Appendix S.1 and Lemma 3 in the Appendix of the paper).

these objects will have received even more offers. Further, by definition, all the $|O_1|+1$ agents (except for one) participating in this stage will be matched to one of their $\kappa(n)$ top choices. Because $\kappa(n)$ is sublinear in n, by the end of Stage 1, these agents will still receive payoffs arbitrarily close to their upper bound when matched to tier 1 objects (this is proven in Online Appendix S.1). Although the first stage is likely to end at Step $|O_1|+1$ and thus involves one more agent than the number of objects, the resulting market is "approximately" balanced, and the competition among agents is still moderate because of the offer bound $\kappa(n)$.[25] The same observation applies to the subsequent Stages, suggesting that a segmentation of the market into balanced submarkets would emerge endogenously under DACB.

Several remarks are in order on the parameter $\kappa(n)$. Unlike the exogenous segmentation, the threshold $\kappa(n)$ does not depend on the precise tier structure of the objects and thus can be implemented without knowing it. Second, there is a fairly broad range of $\kappa(n)$ that produces asymptotic efficiency and asymptotic stability. This means that the performance of DACB is robust to the possible misspecification of $\kappa(n)$ on the part of the designer. Third, the precise range of $\kappa(n)$ will certainly depend on the preference structure, which may depart from that assumed in our model, but, as we illustrate in Section 6, it can be fine-tuned to a specific market based on a careful study of its data. Fourth, as proven in Online Appendix S.7, the convergence is pretty fast. More specifically, the probability that the DACB with a suitably chosen $\kappa(n)$ achieves any desired degrees of efficiency and stability converges at rates faster than $1/n$. In addition, we have performed numerous simulations of the alternative mechanisms for a range of market sizes, and they have shown that DACB performs well in terms of efficiency and stability even for moderate-size markets. The simulation results are available in Online Appendix S.11.1.

While our analysis has assumed that agents' priorities over objects are uncorrelated, one can handle correlations in priorities by approriately selecting the serial order of agents in DACB. Suppose for instance that agents' priorities—more precisely objects' utilities over agents—consist of common values in finite tiers and randomly-drawn idiosyncratic components, just like agents' utilities over objects. Then, the designer can run DACB with a serial order reflecting their priorities; namely, agents with higher common values (high tier) are ordered ahead of agents with lower common values (low tier). The asymptotic efficiency and the asymptotic stability of DACB are then preserved. Of course, this approach requires knowledge about agents' priorities by the designer. Such a knowledge is often available. In school choice, students' priorities are public information and known to the school system (designer).

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[25]Ashlagi, Kanoria, and Leshno (2017) show that a small imbalance of only one agent is enough to increase the average rank enjoyed by the agent from the order of $\log n$ to $n/\log(n)$. While even the latter rank will give rise to a high payoff in our setup, the first stage of DACB differs from the DA with a small imbalance. Due to the bound on the offer, the maximal rank to be enjoyed by the (matched) agents is $\kappa(n)$, which differs from $n/\log(n)$.

Further, our simulations with randomly generated data provided in Online Appendix S.11.2 show that our results, again with the serial order chosen similarly, are robust to more general forms of priorities (and preferences).[26]

One potential drawback of DACB is that it is not strategy proof. In particular, the agent who is eventually unassigned at each Stage may wish to misreport his preferences by including among his κ-best ranked objects a "safe" item that is outside his top κ favorite objects but is unlikely to be popular with other agents. Such misreporting could benefit the agent because the safe item may not have received any other offer and thus would accept him, whereas truthful reporting leaves him unassigned at that stage and results in the agent receiving a possibly worse object.[27]

However, the odds of becoming such an agent is roughly one over the number of agents assigned in the Stage; hence for an appropriate choice of κ and given the *basic uncertainty* over one's serial order, the odds are very small from the perspective of each agent in a large economy. Hence, the incentive problem with the DACB is not very serious. To formalize this idea, we study the Bayesian game induced by DACB. In this game, the set of types for each agent corresponds to his vector of cardinal utilities, i.e., $\{U_i(o)\}_{o \in O}$, or equivalently, $\xi_i := \{\xi_{i,o}\}_{o \in O}$. These values are drawn according to the distributions assumed thus far. The underlying informational environment is Bayesian: each agent only knows his own preferences, labeled his "type," and knows the distribution of others' preferences and the distribution of priorities (including his own).

DACB is an ordinal mechanism, i.e., it maps profiles of ordinal preferences reported by the agents and agents' priorities with objects into matchings. In the game induced by DACB, the set of actions by agent i of a given type ξ_i is the set of all possible ordinal preferences the agent may report. A typical element of that set will be denoted P_i. Each type ξ_i induces an

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[26]When agents' priorities over objects are perfectly correlated, DA and TTC are both equivalent to serial dictatorship where the ordering is given by the common ranking of agents by the objects. Obviously, the outcome is efficient and stable. Interestingly, it is implemented by DACB for any possible κ where the serial order is also given by the common ranking.

[27]This observation can be made precise. Suppose that there are four agents and four objects. Agent 1 prefers o_1 most and o_2 second most, but he has the lowest priority with each of these two objects. Agent 1's third most preferred object is o_3, but he enjoys the highest priority with that object. Agents 2 and 3 rank o_2 and o_3, respectively, at the top of their preference lists, while agent 4 ranks o_1 first. Consider DACB with $\kappa = 2$ for this economy. Suppose first all agents report truthfully, including agent 1. One can verify that agent 1 triggers the end of Stage 1 and is assigned o_4. Specifically, in the first three Steps, agents 1, 2, and 3 apply to o_1, o_2 and o_3, respectively, and are tentatively accepted by them. In Step 4, agent 4 applies to o_1, which keeps him and rejects agent 1. Agent 1 then applies to o_2 and is rejected, at which point Stage 1 ends. In Stage 2, agent 1 is assigned object o_4. Suppose next agent 1 misreports by ranking o_3 among his two most favorite objects. Then, he can guarantee himself o_3. In sum, agent 1 benefits from misreporting his preference, suggesting that truthful reporting is not a Bayes-Nash equilibrium behavior. Nevertheless, we argue below that in the large economy, truthful reporting is a ϵ-Bayes-Nash equilibrium.

ordinal preference that we denote $P_i = P(\xi_i)$. This is interpreted as the truthful report of agent i of type ξ_i. Given any $\epsilon > 0$, truth-telling is an interim ϵ-Bayes-Nash equilibrium if, for each agent i, each type ξ_i and any possible report of ordinal preferences P'_i, we have

$$\mathbb{E}\left[U_i(DACB_i(P(\xi_i), \cdot)) \mid \xi_i\right] \geq \mathbb{E}\left[U_i(DACB_i(P'_i, \cdot)) \mid \xi_i\right] - \epsilon,$$

where $U_i(DACB(P_i, .))$ denotes the utility that i receives when he reports P_i.

THEOREM 5. *Fix any $\epsilon > 0$. Then, under DACB with $\kappa(n) \geq \log^2(n)$ and $\kappa(n) = o(n)$, there exists $N > 0$ such that for all $n > N$, truth-telling is an interim ϵ-Bayes-Nash equilibrium.*

PROOF. See Online Appendix S.8. □

REMARK 1. [Virtual asymptotic strategy-proofness] It is easy to see from our argument that a stronger incentive property can be obtained. Suppose that agents draw their reports according to any arbitrary *iid* distribution which lies in the class of distributions allowed by the current model, hence not necessarily truthfully.[28] Fix any $\epsilon > 0$. Then, under DACB with $\kappa(n) \geq \log^2(n)$ and $\kappa(n) = o(n)$, there exists $N > 0$ such that for all $n > N$, truth-telling is an (interim) ϵ-best response against any such strategy (which is not necessarily truthful). This is reminiscent of Azevedo and Budish (2015)'s notion of "strategy-proofness in the large."

Thus far, the informational environment assumes that each agent only knows his own preferences. One could assume further that the agent's private information contains some additional information such as his priorities. In such a case, agent i's type would be a pair $(\xi_i, \eta_i) := (\{\xi_{i,o}\}_{o \in O}, \{\eta_{i,o}\}_{o \in O})$. Note that DACB still has good incentive properties even in this richer context. Indeed, given any $\kappa(n)$ (i.e., $\kappa(n) \geq \log^2(n)$ and $\kappa(n) = o(n)$), for any $\epsilon > 0$, it is an ex ante ϵ-Bayes-Nash equilibrium to report truthfully when the number of agents is large enough.[29]

To see this, fix $k = 1, ..., K$ and agent with serial order $i \in \{|O_{\leq k-1}| + 2, ..., |O_{\leq k}| + 1\}$ (with the convention that $|O_{\leq 0}| + 2 = 1$ and $|O_{\leq K}| + 1 = n$). As shown in Theorem 4, given truthful reporting by all agents, the agent is assigned one of his $\kappa(n)$ most preferred objects in O_k—and hence enjoys a payoff arbitrarily close to $U(u_k, 1)$—with high probability. Further, given truthful reporting by the other agents, with high probability, Stage $k' < k$ ends before agent i takes his turn, irrespective of his behavior. These two facts imply that a deviation from truthful behavior cannot make the deviating agent ϵ-better off in ex ante terms

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[28]More precisely, let $\{\tilde{\xi}_{io}\}_o$ be a collection of iid random variables drawn from an arbitrary distribution in $[0, 1]$. For any k and $o \in O_k$, draw $U(u_o, \tilde{\xi}_{io})$. Then, the admissible strategy is to report the ordering induced by the realized cardinal utilities. Note that $\{\tilde{\xi}_{io}\}_o$ and $\{\xi_{io}\}_o$ are all independent.

[29]Truthful reporting means reporting one's true preferences *irrespective of one's priorities.* Such a behavior is an ex ante ϵ-Bayes-Nash equilibrium if for any $\epsilon > 0$, the gain from deviating from that behavior is less than ϵ ex ante (i.e., prior to the realization of preferences and priorities) for an n that is sufficiently large.

for sufficiently large n. Hence, truthful reporting is an ex ante ϵ-Bayes-Nash equilibrium. This does not imply that all types (ξ_i, η_i) have incentives for reporting truthfully, but it does imply that "almost all" types of agents will have incentives for truth-telling.

5.2 Extended Algorithm

In many real-world matching mechanisms, applicants are allowed or willing to list only a small number of objects. A case in point is the NYC school choice, wherein an applicant can rank only 12 choices in his/her application. In such cases, our lower bound on $\kappa(n)$ stated in Theorem 4 may in some instances be too large. Hence, we consider a generalization of our mechanism under which a significantly smaller lower bound can be achieved.

The new version of DACB collects preference rankings from agents and assigns them serial orders in the same manner as before. However, it is indexed by two integers j and κ. Termination of a Stage is now triggered whenever there are j individuals, each having made at least κ offers. In other words, we allow up to $j - 1$ individuals to make more than κ offers before the circuit breaker is activated. Obviously, when $j = 1$, we return to our original version of DACB. Under this version of DACB indexed by $j(n)$ and $\kappa(n)$ (where n is the size of the market), we obtain the following result.

THEOREM 6. *If* $\liminf_{n \to \infty} \frac{j(n)\kappa(n)}{n \log(n)} > 1$ *and* $j(n)$ *and* $\kappa(n)$ *are* $o(n)$, *then the matching outcome of DACB is asymptotically efficient and asymptotically stable.*

PROOF. See the Online Appendix S.9. $\square$

REMARK 2. [Relationship with Theorem 4] Theorem 4 is not a special case of Theorem 6. Indeed, for $j(n) = 1$, the above theorem gives $n \log(n)$ as a lower bound on $\kappa(n)$, which is obviously much greater than $\log^2(n)$ and, more generally, has no bite because, trivially, agents rank at most n objects. Theorem 6 is therefore useful only for a sufficiently large j. Finally, the arguments in the proof of each of these two results are distinct.

The new feature of DACB with (κ, j), $j \gg 1$, is that among those taking turns in Stage k, up to j agents will likely fail to receive objects in O_k. However, as the market grows large, j becomes very small relative to the number of agents assigned during that Stage. Hence, given (a suitable generalization of) *basic uncertainty* regarding the serial order, each agent finds the odds of being one of such agents or unmatched negligible in the large economy. This feature ensures that the extended algorithm retains the same desirable incentive properties as the basic algorithm. Specifically, in the Online Appendix S.9, we show that Theorem 5 extends to DACB with (κ, j), satisfying the condition of Theorem 6 (see Theorem S4).

One may be also interested in how the "optimal" choice (κ, j) may depend on the correlation of preferences. While our limit results do not distinguish alternative choices of these

parameters, our simulation performed in Online Appendix S.11.3 reveals that, increased correlation in agents' preferences tends to exacerbate inefficiencies more than instability.[30] This suggests that a designer facing a market with higher preference correlation may choose lower values of κ and j to attain the same tradeoff between efficiency and stability. Of course, the precise choice of design parameters such as κ and j can be tailored to the empirical characteristics of the market. We illustrate such a possibility in Section 6.

5.3 DA with Constrained ROLs

The main feature of DACB—namely, limiting participants' choices—is reminiscent of mechanisms employed in some centralized matching procedure. A prominent example is the DA with constrained ROLs (henceforth DAC), a variant of DA in which applicants' ROLs cannot exceed a fixed length. While DAC is very common in practice,[31] authors have found it difficult to rationalize the constraint on choices.[32] Our perpective recognizes one redeeming quality of this practice in limiting the harmful effect of competition. Indeed, we can show at least in a two-tier model that the DAC admits an ε-Bayesian Nash equilibrium whose outcome is asymptotically efficient and asymptotically stable, *provided that the constraint is chosen appropriately*. This offers some justification for the use of DAC.

To begin, consider DAC with length chosen at $\kappa(n)$ for each n-economy. Then, for each n-economy, DAC induces a Bayesian game in which each agent i's type comprises a vector $\xi_i := (\xi_{io})_o$, and his (pure) strategy maps his type to a ROL of $\kappa(n)$ objects. We are interested in the matching outcome induced by the sequence of strategy profiles adopted by the agents for all n-economies.

THEOREM 7. *Assume that $K = 2$. Consider the DAC with length $\kappa(n)$. Let $\kappa(n) = o(n)$ and satisfy $\kappa(n)/\log^2(n) \to \infty$ as $n \to \infty$. There is a sequence of strategy profiles satisfying the following two properties. (1) For any $\varepsilon > 0$, and n large enough, the strategy profile for each n-economy is an ex-ante ε-Bayes Nash equilibrium, and (2) the induced matching outcome is asymptotically efficient and asymptotically stable.*

While Theorem 7 suggests that DAC may have a similar benefit as DACB, we view the former as inferior to the latter in several respects. First, the DAC does not induce agents to

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[30]As is shown in Online Appendix S.11.3, with increased correlation in preferences, DACB performs worse in both efficiency and stability in *absolute terms*, but its performance improves in *relative terms* compared with DA or TTC.

[31]For example, Chicago, New York City, Ghana, Spain, Turkey adopt DAC in school assignment. See Fack, Grenet, and He (2015) for references.

[32]Calsamiglia, Haeringer, and Klijn (2010) find in their laboratory experiment that constrained choices lead to preference manipulations and unstable matchings. In light of these problems, the practice is viewed as puzzling (see Pathak (2016) for instance).

report truthfully about their preferences. In other words, strategic behavior on the part of agents is necessary to achieve the desirable outcome.[33] By contrast, the DACB is virtually strategyproof in the sense discussed in Remark 1, and hence requires little strategic coordination among agents. Second, the consequence of strategic mistake under DAC can be severe for an agent may simply be unassigned. In DACB, such a risk is mitigated by the feature that those unassigned in any given stage can still participate in the subsequent stage with an additional "budget" of κ offers. Finally, Theorem 7 requires the length of ROLs to be at least $\log^2(n)$, which is often impractically large. We expect the mechanism to perform much worse when the constraint is more realistic. By contrast, DACB can be adapted to work with a "small" number of choices, as suggested in Section 5.2.

REMARK 3 (Chinese parallel mechanism). As we already pointed out, a drawback of the DAC is that once a student exhausts her (constrained) ROL he gets unassigned. DACB mitigates this risk by "replenishing" the choice quota for students unassigned after each stage. Alternatively, one can repeat the DAC in multiple stages: in each stage all remaining agents participate in a DAC with some length κ. This is precisely what Chen and Kesten (2017) calls (symmetric) Chinese-parallel mechanism.[34] A result similar to Theorem 7 would apply to this mechanism for an appropriately chosen κ. While this mechanism mitigates the strategic risks facing participants better than DAC, it will not eliminate them, particularly for a realistic level of κ. By comparison, the (extended) DACB virtually eliminates the risk and thus incentivizes the agents to report truthfully.[35]

6 Field Application: NYC School Choice

Thus far, we have considered a large one-to-one matching market (in the limiting sense) with a class of random preferences and priorities. Real-world matching markets often depart from this model; for instance, school choice involves many-to-one matching. Further, the size of the market may not be very large. Our theory may not apply exactly in these settings.

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[33]Note further that notion of equilibrium here is "ex ante" ε-Bayesian Nash equilibrium, which is not as satisfactory as "interim" ε-Bayesian Nash equilibrium used for DACB.

[34]As noted in Chen and Kesten (2017), the mechanisms used for assigning students to Chinese universities are slightly different. College programs are partitioned into several tiers differing in "prestige." And, the Chinese parallel mechanism is run first for the first-tier (most prestigious) colleges. Next, those unassigned move to the second round, where the same mechanism is run for the second-tier colleges. The same process is repeated for each subsequent tier. See also Wu and Zhong (2014) for additional details.

[35]More precisely, under the Chinese-parallel mechanism, if all agents were to report truthfully, a significant number of agents (i.e., linear in n) would be active (i.e., make offers) but end up unassigned in each round (except for the final) for any $\kappa(n)$ sublinear in n. This means that each participant faces a significant incentive to manipulate preferences by moving up safe items in his ROL. By contrast, in DACB, only a small (sublinear) number of active agents get unassigned in each stage when reporting truthfully.

Nevertheless, it is interesting to assess whether DACB could offer a more desirable compromise on the tradeoff between efficiency and stability in such a case. We thus study the school choice in NYC.

In New York City, each year approximately 80,000 middle school students (mostly 8th graders) are assigned to over 700 public high school programs through a centralized matching process. The process involves multiple rounds, but the main round employs the deferred acceptance algorithm to assign participants to programs in several categories: *screened, limited unscreened, unscreened, ed-op, zoned* and *audition*.[36] Each participant in the main round may submit a rank-order list (ROL) of up to 12 programs, and each program ranks applicants— who listed the program in their ROLs—according to its priority criteria, which depend on the type of the program. The priorities are coarse for many programs, and ties are broken by a single (uniform) lottery for all programs.[37]

Our analysis focuses on the main round of the 2009-2010 assignment. We calibrate the performances of DACB with several (κ, j)'s against DA and TTC as benchmarks. In so doing, we take two different approaches.

- **Counterfactual based on observed ROLs**: This approach postulates that applicants would submit the same ROLs under counterfactual scenarios as they submitted under the NYC matching.

- **Counterfacutal based on structual estimates of preferences**: This approach structurally estimates the preferences of applicants and simulates their ROLs under counterfactual scenarios, assuming that all programs are acceptable.

The first approach essentially rests on the following two assumptions: (i) that the programs in ROL are truthfully ranked and dominate all other unranked ones; and (ii) that the unranked programs are not acceptable for the applicants. Assumption (i), often called *weak truth-telling*, is a standard assumption made when dealing with a strategyproof mechanism such as DA.[38]

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[36]Assignment to the so-called specialized "exam" schools is processed through the first round, which takes place before the main round. Since 2010, the first round and the main round have been merged into a single round, but the process for the main round remains unchanged.

[37]It is known that if none of the schools strictly rank students, DA with a single tie-breaking rule is efficient. However, for arbitrary coarse priorities, DA with single tie-breaking may not be efficient and may not even yield a student-optimal stable matching. See, for instance, Example 1 in Abdulkadiroglu, Pathak, and Roth (2009).

[38]This assumption is not entirely innocuous though since the strategy-proofness of DA does not apply when the applicants' ROLs are truncated (see Haeringer and Klijn (2009)). Nevertheless, about 80% of participants do not fill up their ROLs, suggesting that the truncation is not binding. A similar approach is followed by Abdulkadiroglu, Agarwal, and Pathak (2015), Abdulkadiroglu, Pathak, and Roth (2009) and Abdulkadiroglu, Che, Pathak, Roth, and Tercieux (2017).

Assumption (ii) is more controversial since the presence of a supplementary round means that some applicants may not list all acceptable programs in the main round. In fact, as many as 5,241 students out of 5,611 unassigned by the end of the main round listed new additional programs in a supplementary round. For this reason, the observed ROLs do not typically include all acceptable programs. In other words, this method postulates too "short" an ROL for an applicant. As will be seen, the short ROLs will *understate* the effect of competition, and therefore the tradeoff between efficiency and stability and the performance of DACB.

This problem motivates the second approach—the structural estimation method based on Abdulkadiroglu, Agarwal, and Pathak (2015) (henceforth AAP)—which invokes only the weak truth-telling assumption (i). Under this approach, we first estimate (random) utilities as functions of student and program characteristics, and use the estimates to "draw" the applicants' ROLs. One advantage of this approach is that we can actually represent the true DA, without any constraints on ROLs or a follow-up supplementary round, just as considered in the theory. At the same time, since the AAP method does not consider outside options, the simulated/predicted ROLs would include *all* programs, including those that applicants may find unacceptable. Hence, this method posits too "long" an ROL for an applicant. As will be seen, this feature will tend to *overstate* the effect of competition, and therefore the tradeoff between efficiency and stability and the performance of DACB.

In sum, the two approaches allow us to provide (lower and upper) bounds on the relative performance of DACB, and the tradeoff between DA and TTC. We thus view them as mutually complementary. We now present the results for each of the two approaches described above.[39]

6.1 Comparison of Mechanisms Based on Observed ROLs

Table 1 describes average performances of alternative algorithms according to various measures.[40]

The first row describes, for each mechanism, the average number of students who can be made better off from a Pareto-improving reassignment of the original outcome using the Shapley-Scarf TTC. This number is zero for an efficient matching algorithm such as TTC.

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[39]A student's priorities at alternative NYC schools are likely to be correlated. As we already suggested, in such an environment, one can improve the performance of DACB by adjusting the agents' serial orders to reflect their average priorities. In the subsequent analysis, we ignore this possibility and simply employ a random serial ordering. In a previous version of this work (Che and Tercieux (2015)), we also measured the performance of DACB when the serial order reflects the agents' priorities. As expected, the performance is significantly better. In this sense, the subsequent results understate the potential benefit of the DACB if one can "optimize" serial orders.

[40]The average here is taken over 100 independent draws of a single lottery used to break ties in schools' priorities. In particular, this means that the values reported for DA does not coincide with the realized outcome in 2009-10 assignment.

Table 1: The efficiency and stability of alternative mechanisms

	DA	DACB-$(2, 20000)$	DACB-$(4, 2000)$	DACB-$(6, 1)$	TTC
# Pareto Improvable	5189.89 (241.98)	3654.19 (80.07)	2409.60 (65.56)	449.43 (64.89)	0
# students with envy	0	2041.05 (179.83)	4620.43 (251.46)	13268.26 (502.03)	18943.21 (324.67)
# assigned to top choice	40370.88 (389.10)	41696.43 (239.16)	42966.22 (208.03)	45098.69 (190.77)	45109.77 (200.80)
# unassigned	4362.98 (166.72)	4645.11 (175.51)	4978.56 (176.47)	5601.75 (161.91)	5624.98 (158.68)

Note: We ran 100 iterations of each algorithm with independent draws of lotteries, and focus on the average performance of each algorithm, including DA. The numbers inside the parentheses are standard errors.

Arguably, the larger this number is the more inefficient a matching is. Hence, this number can be interpreted as a measure of inefficiency. The second row counts the number of agents with justified envy (i.e., who are part of at least one blocking pair) in each mechanism. Obviously, DA admits no such agent. As expected, TTC may admit a large number of agents with justified envy.[41] DACB provides a compromise between DA and TTC, yielding higher efficiency than DA and lower instability (i.e., fewer incidences of justified envy) than TTC.

As noted, the DACB is flexible enough to admit many new options to the designer's arsenal of policy tools. Figure 2-(a) depicts the range of ways in which the tradeoff between efficiency and stability is resolved via DACB with various (κ, j)'s. In these figures, efficiency (the vertical axis) is measured as the percentage of agents who cannot be made better off through Pareto-improving reallocation, while stability (the horizontal axis) is measured as the percentage of students who do not have any justified envy.[42]

Not surprisingly, DA and TTC occupy the southeast and northwest extreme corners of the figure. In between the two, DACB with various (κ, j) values spans a rich array of compromises between the objectives. As expected, the efficiency of DACB increases as κ falls, while its stability increases as κ rises. The "frontier" is outside the linear segment between DA and TTC, suggesting that the outcomes of DACB are superior to a simple convexification of DA and TTC.

As we already argued, the short ROLs observed in the data means that the exercise understates the true competition that applicants will have under unrestricted DA. Thus,

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[41]Serial dictatorship which corresponds to DACB with $(\kappa, j) = (1, 1)$ totally ignores the school priorities and admits slightly more agents with envy than TTC.

[42]Specifically, efficiency is defined as $1 - \dfrac{\# \text{ of Pareto-improvable agents}}{\# \text{ of total agents}}$ where the # of Pareto-improvable agents corresponds to the number of agents who are better off when running Shapley-Scarf TTC on top of the mechanism. As for stability, our percentage is defined by $1 - \dfrac{\# \text{ of agents with envy}}{\# \text{ of total agents}}$ where the # of agents with envy corresponds to the # of agents who are part of at least one blocking pair.
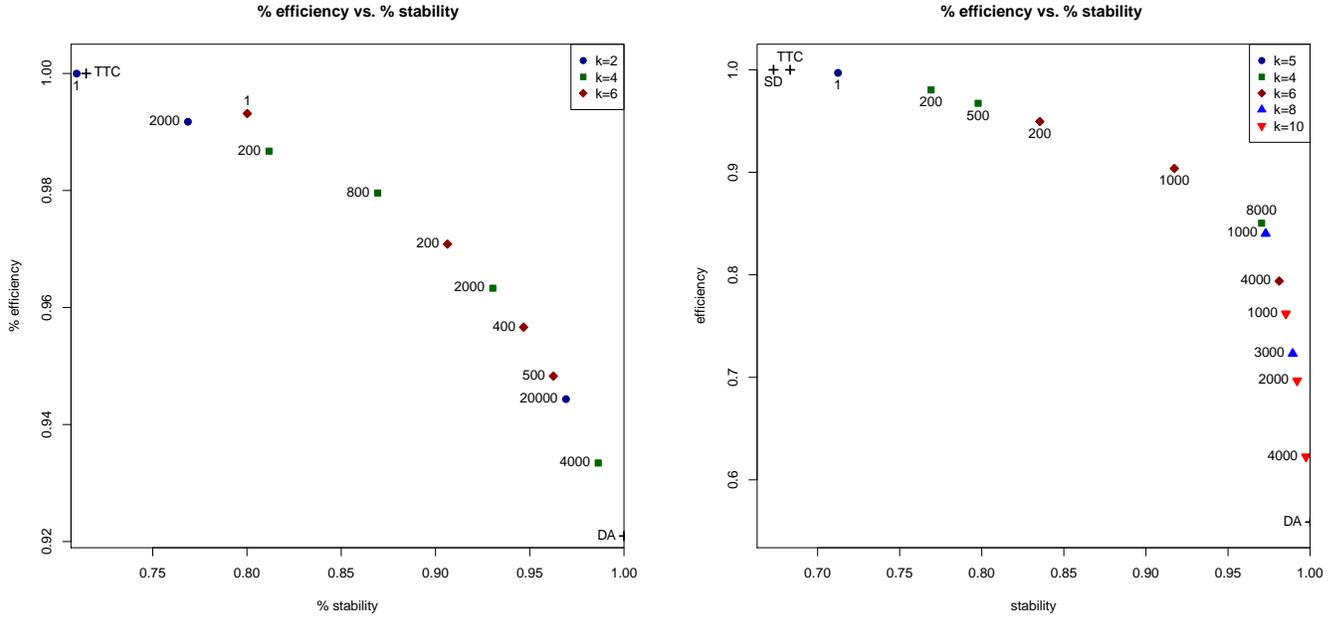
(a) Based on Observed ROLs

(b) Based on Structural Estimates

Figure 2: Efficiency vs. Stability: based on two methods (in ordinal measures).

Note: The shape of each coordinate corresponds to κ, while the associated integer refers to parameter j.

our calibration potentially overstates the efficiency performance of DA. Likewise, the short ROLs also mean that our calibration is likely to "miss" incidences of justified envy that will arise under TTC, meaning it overstates the stability of TTC. Overall, the calibration may understate the magnitude of the tradeoff between efficiency and stability and therefore understate the relative performance of DACB.

In sum, the above results can be interpreted as conservative estimates of the tradeoff between DA and TTC and the benefits achievable from DACB.

6.2   Comparison of Mechanisms Based on Structural Estimates

In this section, we use demand estimation for school programs to draw applicants' ROLs. To this end, we estimate a random utility model. In this model, the utility of student i for school program j is given by

$$u_{ij} = \delta_j + \sum_{\ell} \alpha^{\ell} z_i^{\ell} x_j^{\ell} + \sum_k \gamma_i^k x_j^k - d_{ij} + \epsilon_{ij}, \tag{2}$$

where $\delta_j = \mathbf{x_j}\beta + \xi_j$, $\mathbf{x_j}$ is a vector of program j's observed characteristics, $\mathbf{z_i}$ is a vector of observed students' characteristics, ξ_j is a program-specific unobserved vertical characteristic,

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γ_i captures idiosyncratic tastes for program characteristics and ϵ_{ij} captures idiosyncratic tastes for programs. Finally, d_{ij} is the distance measured in miles between student i and program j's geographic locations. We further assume that $\gamma_i \sim \mathcal{N}(0, \Sigma_\gamma)$, $\xi_j \sim \mathcal{N}(0, \sigma_\xi^2)$ and $\epsilon_{ij} \sim \mathcal{N}(0, \sigma_\epsilon^2)$. The vector of parameters we estimate is $(\alpha, \beta, \Sigma_\gamma, \sigma_\xi^2, \sigma_\epsilon^2)$. As noted by AAP, this model is an ordered choice version of the model used by Rossi, McCulloch, and Allenby (1996), who show that these distributional assumptions allow for estimation via Gibb's sampling.[43] The specification treats distance as a numeraire: the coefficient -1 on distance is a scale normalization (assuming students dislike to travel) which allows us to measure utility in distance units. We use the same location normalization as AAP: a student's utility for a school is equal to zero if the school is located at zero distance from his home and if his student characteristics and the school characteristics are all zero. Hence, this normalization facilitates comparison with their results and thus interpretation of our results. Also, given that we are mainly interested in comparisons across mechanisms, a particular choice of location normalization is irrelevant.

School program characteristics include the math achievement of the student body, the percentage of students receiving subsidized lunch, the percentage of white students, the size of 9th grade, a dummy indicating a language-focused program (coded as Asian, Spanish or others) and a dummy on the program type.[44] Student characteristics include academic performance (in math and English), ethnicity, a subsidized lunch status, neighborhood income, proficiency in English and a special ed status.

Our estimates are reported in Online Appendix S.13. They are largely consistent with those found by AAP based on 2003-2004 data. More important, the sign and magnitude of parameters are reasonable and intuitive. We use these estimates to draw each student's ROLs according to (2) as well as his/her priorities (which includes single tie-breaking lottery).[45] With these as inputs, we simulate alternative algorithms, including DA (without truncation and without the supplementary round), TTC, and DACB with various (κ, j)'s. We compute the average performance of each mechanism over 100 realizations of these random draws.

Table 2 reports the analogues of Table 1. The first three rows are the same as the corresponding rows in Table 1, measuring the number of students who can be made better-off from a Pareto-improving reassignment, the number of students with justified envy and the number

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[43]See the online appendix of AAP for details.

[44]The NYC high school directory describes numerous program types. As in AAP, these program types were aggregated into different categories: Arts, Humanities/Interdisciplinary, Business / Accounting, Math / Science, Career, Vocational, Government/law, Zoned and Others.

[45]There are two reasons why students' priorities are random. First, priorities at school programs can be coarse and we use a single tie-breaking rule to break ties. Second, as explained in the supplementary material (see Section S.12), we had to estimate the distribution of priorities of students (as a function of students' observables) at schools which are not in their observed ROLs.

Table 2: The efficiency and stability of alternative mechanisms

	DA	DACB-(8, 3000)	DACB-(4, 8000)	DACB-(4, 200)	TTC
# Pareto Improvable	29293.28 (339.54)	18382.59 (141.92)	9931.34 (101.85)	1299.98 (62.09)	0
# students with envy	0	703.73 (20.33)	1963.13 (32.89)	15329.54 (162.49)	21029.31 (250.66)
# assigned to top choice	23823.26 (215.65)	30671.82 (102.43)	36502.27 (71.70)	43674.35 (64.08)	44060.72 (48.77)
average welfare	-2.63 (0.031)	-1.93 (0.006)	-1.60 (0.006)	-1.38 (0.008)	-1.31 (0.005)
average justified envy	0	0.11 (0.004)	0.25 (0.006)	0.99 (0.011)	1.28 (0.018)

Note: We ran 100 iterations of each algorithm with independent draws of lotteries, and focus on the average performance of each algorithm, including DA. The numbers inside the parentheses are standard errors.

of students getting their top choice, all averaged over 100 iterations.[46]

The "competition" effect of long lists is apparent: TTC performs considerably worse in stability than in Table 1 (2,000 more applicants would suffer justified envy), and DA performs considerably worse than in Table 1 (about 25,000 more students would benefit from a Pareto-improvement). In particular, this means that the DA employed in NYC performs much better in efficiency than the "true" DA simulated in Table 2, suggesting that the NYC mechanism might already provide a compromise between efficiency and stability.[47] Of course, DACB is expected to perform this role, and it does impressively, as can be seen in the three middle columns. For instance, DACB with $(\kappa, j) = (8, 3000)$ yields considerably higher welfare with very little sacrifice in stability, compared with DA. In general, Figure 2-(b) promises a much more significant improvement to be achievable by DACB, compared with Figure 2-(a).

So far, we have used our cardinal utility estimates only to predict ordinal performances of alternative mechanisms. We can also measure their performances in cardinal utilities. The penultimate row of Table 2 measures the average (utilitarian) welfare of students for each mechanism, and the last row measures the average justified envy in terms of utility gain from fulfilling one's justified envy.[48] Figure 3 replicates Figure 2-(b) using cardinal measures of efficiency and stability. Here again, DACB with various (κ, j)'s spans a rich

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[46]As explained in the Online Appendix (Section S.12), the number of seats equals the number of students. Since we assume students rank all programs in our counterfactual analysis, there are no unassigned students under the mechanisms we study.

[47]Strictly speaking, to measure the inefficiency of the mechanism used in NYC, we should also look at the outcome in the supplementary round. However, even if we take a worst-case approach and add the number of unassigned agents of DA obtained in Table 1 to the number of Pareto-improvable agents obtained in that same table, it remains considerably smaller than the number of Pareto-improvable students for DA obtained in Table 2.

[48]For each student, we compute the utility difference between his assignment and his most preferred school program with which he could block. We then average this number over all students.
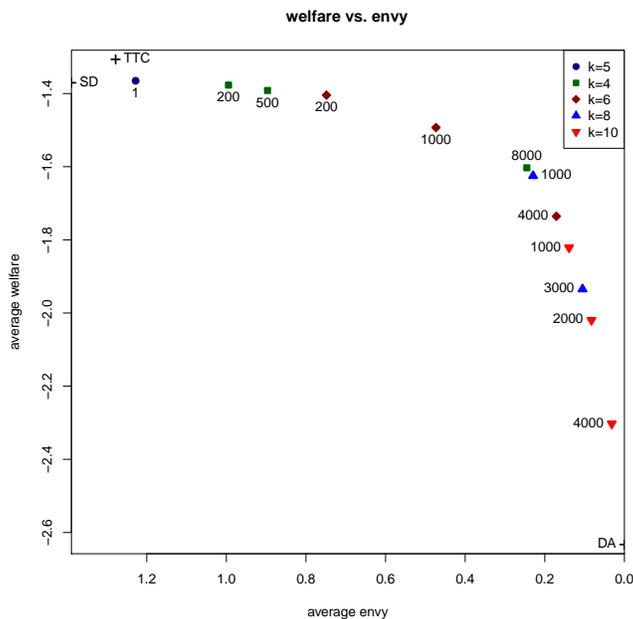
Figure 3: Efficiency vs. Stability: based on structual estimates (in cardinal measures).

Note: The shape of each coordinate corresponds to κ, while the associated integer refers to parameter j.

array of compromises between efficiency and stability. As with Figure 2-(b), the "frontier" is significantly curved, suggesting the potential for DACB to act as desirable compromise on efficiency and stability.

To conclude, these outcomes provide a rich set of new choices from which a policy maker can choose. A careful study of data, as illustrated here, could help a policy maker to tailor the design of DACB to fit his/her sense of the social weighting of the two objectives.

7   Concluding Remarks

The current paper has studied the tradeoff between efficiency and stability—two desiderata in market design—in large markets. The two standard design alternatives, Gale and Shapley's deferred acceptance (DA) and top trading cycles (TTC), each satisfy one property but fail to satisfy the other. Considering a plausible class of situations in which individual agents have preferences drawn randomly according to common and idiosyncratic shocks and priorities drawn in an *iid* fashion, we show that these failures—the inefficiency of DA and instability of TTC—remain significant even in large markets.

We have therefore proposed a new mechanism, deferred acceptance with a circuit breaker

(DACB), which modifies DA to keep agents from competing excessively for over-demanded objects—a root cause of DA's significant efficiency loss in a large market. Specifically, the proposed mechanism builds on McVitie and Wilson's version of DA in which agents make offers one at a time along a predetermined serial order. However, during the process, whenever an agent makes a certain threshold number of offers for the first time, the process is stopped, and what had been a tentative assignment up to that point is finalized. Thereafter, a new stage of the serialized process is begun with the remaining agents and objects, again with the same circuit-breaker feature, and this process is repeated until all agents are processed. We have shown that DACB with suitably chosen parameters κ achieves both efficiency and stability in an approximate sense as the economy grows large, and it induces truth-telling in an ϵ-Bayes-Nash equilibrium.

Although our analytical model is not without restriction, our analysis of the NYC school choice data validates our overall findings. Specifically, we have found that the inefficiencies of DA and instabilities of TTC are significant and that DACB offers viable compromises on the tradeoff between efficiency and stability. In addition, the numerous simulations we performed (available in our Online Appendix S.11) confirm that the main results hold well beyond the setting we study and in particular for market sizes that are quite moderate. In that respect, it is interesting to compare our results with those obtained by Lee and Yariv (2017). They show that *stable* mechanisms are asymptotically efficient in a balanced market if the agents' preferences and priorities have common shocks distributed continuously over an interval. By contrast, Ashlagi, Kanoria, and Leshno (2017) and the current paper note that DA is likely to be asymptotically inefficient when there is competition among agents for desirable objects—either because of a scarcity of objects (when there is imbalance) or because of a positive correlation in agents' preferences. Indeed, Online Appendix S.11.2 shows that the inefficiency of DA vanishes very slowly even in the environment of Lee and Yariv (2017) and that the magnitude of the difference between DACB and DA can be considerable for realistic market sizes. Recall also our analysis of NYC school choice, which shows that DA entails a significant efficiency loss compared with DACB.[49] Finally, and potentially more important, our results regarding the asymptotic efficiency and asymptotic stability of DACB are robust to the introduction of market imbalances, which is not the case for DA.

Another important design parameter of DACB is the threshold number of offers that triggers assignment. Here, again, it can be optimized relative to the detailed features of the market in question. While theoretical results show that DACB achieves an asymptotically efficient and stable outcome when the market grows arbitrarily large, for a finite market, there will always remain some (potentially small) trade-off between the two objectives. Our calibration work on NYC as well as our simulations reported the in Online Appendix S.11 show

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[49]See also Che and Tercieux (2017b) for a discussion of the inefficiencies of DA in the Lee and Yariv (2017) environment, particularly compared with standard efficient mechanisms.

that DACB offers a range of possible compromises between efficiency and stability depending on the specific value of the trigger chosen by the designer. Thus, the serial order of agents and the condition that triggers the circuit breaker can be fine-tuned toward the specifics of a given market.

Finally, our proposed mechanism shares several features of mechanisms that are already in use. As discussed, the truncation of the ROLs is another common feature employed in many centralized matching procedures (see Haeringer and Klijn (2009), Calsamiglia, Haeringer, and Klijn (2010) and Ashlagi, Nikzad, and Romm (2015)). The "staged" clearing of markets is observed in matching markets such as college admissions in China. To some extent, NYC is also using such staged clearing: DA with truncation is used in a first round and, in a supplementary round, it is again used for unmatched students and remaining seats. The current paper sheds some light on the roles that these features may play, particularly in mitigating the harmful effect of excessive competition among participants, and suggests a method for harnessing these features without jeopardizing participants' incentives.

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Appendix: Proof of Theorem 4

Fix any $\kappa(n) \geq \log^2(n)$ and $\kappa(n) = o(n)$. The following proposition is crucial for the proof.

PROPOSITION 1. *Fix any $k \geq 1$. As $n \to \infty$, with probability approaching one, Stage k of the DACB ends at Step $|O_k| + 1$ and the set of assigned objects at that stage is O_k. In addition, for any $\epsilon > 0$:*

$$\frac{|\{i \in I_k | U_i(DACB(i)) \geq U(u_k, 1) - \epsilon\}|}{|I_k|} \xrightarrow{p} 1$$

where $I_k := \{i \in I | DACB(i) \in O_k\}$. Similarly:

$$\frac{|\{o \in O_k | V_o(DACB(o)) \geq V(1) - \epsilon\}|}{|O_k|} \xrightarrow{p} 1.$$

Recall that Lemma 2 gives a sense in which, in the uncorrelated case, the average rank achieved by objects under DA is small relative to the size of the market. In the sequel, we will need the following lemma which shows the implications of this for the values of $V_o(DA(o))$ in such an environment.

LEMMA 3. *Fix any $\epsilon > 0$. In the uncorrelated case,*

$$\frac{|\{o \in O | V_o(DA(o)) \geq V(1) - \epsilon\}|}{|O|} \xrightarrow{p} 1.$$

PROOF. Fix $\epsilon, \gamma > 0$. We first claim that, with probability going to 1, the proportion of objects in O that achieve a rank below $\frac{2}{1-\gamma} |O| / \log(|O|)$ is greater than γ. To prove this, suppose to the contrary that with probability bounded away from 0, as the market grows, the proportion of objects enjoying ranks above $\frac{2}{1-\gamma} |O| / \log(|O|)$ is greater than $1 - \gamma$. Then, with probability bounded away from 0, as the market grows,

$$\frac{1}{|O|} \sum_{o \in O} R_o^{DA} > \frac{1}{|O|} (1 - \gamma) |O| \frac{2}{1 - \gamma} (|O| / \log(|O|)) = 2|O| / \log(|O|),$$

which yields a contradiction to Lemma 2. Hence, with probability going to 1, the proportion of objects in O enjoying ranks below $\frac{2}{1-\gamma} |O| / \log(|O|)$ is larger than γ. Since, for any $\delta > 0$, $|O| / \log(|O|) \leq \delta |I|$ for a sufficiently large n, by Lemma S1-(iii) we must also have that, with probability going to 1, the proportion of objects o in O with $V_o(DA(o)) \geq 1 - \epsilon$ is above γ. $\square$

Proof of Proposition 1. We focus on $k = 1$; the other cases can be treated in exactly the same way.

First, consider the submarket that consists of the $|O_1|$ first agents (according to the ordering given in the definition of DACB) and of all objects in O_1. If we were to run standard DA

just for this submarket, then because preferences are drawn *iid*, by Lemma 2, with probability approaching 1 as $n \to \infty$, *all* agents would have made fewer than $\log^2(n)$ offers at the end of (standard) DA.

Consider now the original market. For any $\delta > 0$, as $\kappa(n) = o(n)$, we must have $\kappa(n) \le \delta |O_1|$ for any sufficiently large n. Hence, by Lemma S1-(ii), the event that all agents' $\kappa(n)$ favorite objects are in O_1 has probability approaching 1 as $n \to \infty$. Let us condition on this event, labeled $\mathcal{E}$. Given this conditioning event $\mathcal{E}$, under DACB, no object outside O_1 would receive an offer before someone reaches his $\kappa(n)$-th offer.

We first show that conditional on $\mathcal{E}$ *all* objects in O_1 are assigned by the end of Stage 1 with probability approaching 1 as $n \to \infty$. Note that under our conditioning event $\mathcal{E}$, the distribution of individuals' preferences over objects in O_1 is the same as the unconditional one (and the same is true for the distribution of objects' priorities over individuals). Given event $\mathcal{E}$, provided that all agents have made fewer than $\kappa(n)$ offers, the $|O_1|$ first steps of DACB proceed exactly in the same way as in DA in the submarket composed of the $|O_1|$ first agents (according to the ordering used in DACB) and of all objects in O_1 objects. Since $\kappa(n) \ge \log^2(n)$, by Lemma 2, with probability going to 1 as $n \to \infty$, we reach the end of Step $|O_1|$ of DACB before Stage 1 ends (i.e., before any agent has applied to his $\log^2(n) \le \kappa(n)$ most favorite object). Thus, with probability going to 1, the outcome thus far coincides with that attained in DA in the submarket composed of the $|O_1|$ first agents and of all objects in O_1. This implies that, conditional on $\mathcal{E}$, with probability going to 1, *all* objects in O_1 are assigned, and thus, Step $|O_1| + 1$ must be triggered.

We next show that conditional on $\mathcal{E}$ Stage 1 ends at Step $|O_1| + 1$ with probability approaching 1 as $n \to \infty$. Since not all of the first $|O_1| + 1$ agents can receive objects in O_1, given $\mathcal{E}$, once Step $|O_1| + 1$ is reached, some agent *must* reach his $\kappa(n)$-th offer, having made offers only to objects in O_1 until then.

Now recall $\Pr(\mathcal{E}) \to 1$ as $n \to \infty$. Combining the preceding observations, therefore, the probability that the circuit breaker is triggered during Step $|O_1| + 1$, thus ending Stage 1, after all objects in O_1 have been assigned by then, goes to one as $n \to \infty$. This completes the proof of the first part of Proposition 1.

Now, we turn to the second part of the proof of Proposition 1. (Recall, we are still considering $k = 1$.) We fix any ϵ and $\gamma < 1$ and wish to show that as $n \to \infty$:

$$\Pr \left\{ \frac{|\{i \in I_1 | U_i(DACB(i)) \ge U(u_1, 1) - \epsilon\}|}{|I_1|} > \gamma \right\} \longrightarrow 1$$

and

$$\Pr \left\{ \frac{|\{o \in O_1 | V_o(DACB(o)) \ge V(1) - \epsilon\}|}{|O_1|} > \gamma \right\} \longrightarrow 1.$$

In the sequel, we condition on event $\mathcal{E}$. First, by construction, every matched individual in

Stage 1 obtains an object within his/her $\kappa(n)$ most favorite objects which by Lemma S1-(i) implies that, with probability going to 1, they *all* enjoy payoffs above $U(u_1, 1) - \epsilon$.[50] This proves the first statement.

We next prove the second statement again for $k = 1$. As we have shown, with high probability, the first $|O_1|$ Steps (i.e., Stage 1) of DACB proceed exactly the same way as in DA in the submarket that consists of the $|O_1|$ first agents and of all objects in O_1, where individuals' preferences and objects' priorities are drawn according to the unconditional distribution (which in this submarket is uncorrelated). According to Lemma 3, under DA in this submarket, with probability going to 1, the proportion of objects o in O_1 with $V_o(DA(o)) \geq 1 - \epsilon$ is above γ. Because objects in O_1 will have received even more offers at the end of Stage 1 of DACB than under the DA in the corresponding subeconomy, it must still be the case that, at the end of that stage, with probability going to 1, the proportion of objects in O_1 for which $V(DACB(o)) \geq 1 - \epsilon$ is above γ when n is large enough. Thus, for $k = 1$, the second statement in Proposition 1 is proven provided that our conditioning event $\mathcal{E}$ holds. Because this event has probability going to 1 as $n \to \infty$, the result must hold even without the conditioning. Thus, we have proven Proposition 1 for the case $k = 1$.

Consider next Stage $k > 1$. The objects remaining in Stage k have received no offers in Stages $j = 1, ..., k - 1$ (otherwise, the objects would have been assigned during those stages). Hence, by the principle of deferred decisions, we can assume that the individuals' preferences over those objects are yet to be drawn at the beginning of Stage k. Similarly, we can assume that the priorities of those objects are also yet to be drawn. In other words, conditional on Stage $k - 1$ being complete, we can assume without loss of generality that the distribution of preferences and priorities is the same as the unconditional one. Thus, we can proceed inductively to complete the proof. □

Given Proposition 1, Theorem 4 follows straightforwardly. The first statement means that with high probability, all but a vanishing fraction of agents realize arbitrarily close to the highest idiosyncratic payoff. This implies that the proportion of the agents who would benefit discretely from a Pareto-dominating reassignment of DACB must vanish in probability. This observation, together with the second statement of Proposition 1, implies that the fraction of agent-object pairs that would gain discretely from blocking the DACB matching also vanishes in probability. The formal proof is in the Online Appendix S.6.

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[50]Note that this implies $\Pr\left[\{i \in I_1 | U_i(DACB(i)) \geq U(u_1, 1) - \epsilon\} = I_1\right] \to 1$ as $n \to \infty$. Hence, part of the statement of Proposition 1 can be strengthened.